Valuing Options in Heston’s Stochastic Volatility Model: Another Analytical Approach

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Abstract

We are concerned with the valuation of European options in Heston’s stochastic volatility model with correlation. Based on Mellin transforms we present new closed-form solutions for the price of European options and hedging parameters. In contrast to Fourier-based approaches where the transformation variable is usually the log-stock price at maturity, our framework focuses on transforming the current stock price. Our solution has the nice feature that similar to the approach of Carr and Madan (1999) it requires only a single integration. We make numerical tests to compare our results to Heston’s solution based on Fourier inversion and investigate the accuracy of the derived pricing formulae.

Keywords: Stochastic volatility, European option, Mellin transform.
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1 Introduction

The pricing methodology proposed by Black and Scholes (1973) and Merton (1973) is maybe the most significant and influential development in option pricing theory. However, the assumptions underlying the original works were questioned ab initio and became the subject of a wide theoretical and empirical study. Soon it became clear that extensions are necessary to fit the empirical data. The main drawback in the original Black/Scholes/Merton (BSM) model is the assumption of a constant volatility. To reflect the empirical evidence of a non-constant volatility and to explain the so-called volatility smile different approaches were developed. Dupire (1994) applies a partial differential equation (PDE) method and assumes that volatility dynamics can be modeled as a deterministic function of the stock price and time.

A different approach is proposed by Sircar and Papanicolaou (1999). Based on the PDE framework they develop a methodology that is independent of a particular volatility process. The result is an asymptotic approximation consisting of a BSM-like price plus a Gaussian variable capturing the risk from the volatility component.

The majority of the financial community, however, focuses on stochastic volatility models. These models assume that volatility itself is a random process and fluctuates over time. Stochastic volatility models were first studied by Johnson and Shanno (1987), Hull and White (1987), Scott (1987), and Wiggins (1987). Other models for the volatility dynamics were proposed by Stein and Stein (1991), Heston (1993), Schöbel and Zhu (1999), and Rogers and Veraart (2008). In all these models the stochastic process governing the asset price dynamics is driven by a subordinated stochastic volatility process that may or may not be independent.

While the early models couldn’t produce closed-form formulae, it was Stein and Stein (1991) (S&S) who first succeeded in deriving an analytical solution. Assuming that volatility follows a mean reverting Ornstein-Uhlenbeck
process and is uncorrelated with asset returns they present an analytic expression for the density function of asset returns for the purpose of option valuation. Schöbel and Zhu (1999) generalize the S&S model to the case of non-zero correlation between instantaneous volatilities and asset returns. They present a closed-form solution for European options and discuss additional features of the volatility dynamics.

The maybe most popular stochastic volatility model was introduced by Heston (1993). In his influential paper he presents a new approach for a closed-form valuation of options specifying the dynamics of the squared volatility (variance) as a square-root process and applying Fourier inversion techniques for the pricing procedure. The characteristic function approach of Heston (1993) turned out to be a very powerful tool. As a natural consequence it became standard in option pricing theory and was refined and extended in various directions (Bates (1996), Carr and Madan (1999), Bakshi and Madan (2000), Lewis (2000), Lee (2004), Kahl and Jäckel (2005), Kruse and Noegel (2005), Fahrner (2007) or Lord and Kahl (2007) among others). See also Duffie et al. (2000) and Duffie et al. (2003) for the mathematical foundations of affine processes.

Besides Fourier and Laplace transforms there are other interesting integral transforms used in theoretical and applied mathematics. Specifically, the Mellin transform gained great popularity in complex analysis and analytic number theory for its applications to problems related to the Gamma function, the Riemann zeta function and other Dirichlet series. Its applicability to problems arising in finance theory has not been studied much yet (Panini and Srivastav (2004) and Frontczak and Schöbel (2008)). The purpose of the paper is to show how this approach can be extended to the stochastic volatility problem. We derive an equivalent representation of the solution and discuss its interesting features.

The article is structured as follows. In Section 2 we give a formulation of the pricing problem for European options in the square root stochastic volatil-
ity model. Based on Mellin transforms the solution for puts is presented in Section 3. Section 4 is devoted to further analysis of our new solution. We provide a direct connection to Heston’s pricing formula and give closed-form expressions for hedging parameters. Also, an explicit solution for European calls is presented. Numerical calculations are made in Section 5. We test the accuracy of our closed-form solutions for a variety of parameter combinations. Section 6 concludes this article.

2 Problem Statement

Let \( S(t) = S_t \) be the price of a dividend paying stock at time \( t \) and \( V_t \) its instantaneous variance. Following Heston (1993) we assume that the risk neutral dynamics of the asset price are governed by the system of stochastic differential equations (SDEs):

\[
\begin{align*}
    dS_t &= (r - q) S_t \, dt + \sqrt{V_t} S_t \, dW_t, \quad (2.1) \\
    dV_t &= \kappa(\theta - V_t) dt + \xi \sqrt{V_t} \, dZ_t, \quad (2.2)
\end{align*}
\]

with initial values \( S_0, V_0 \in (0, \infty) \) and where \( r, q, \kappa, \theta, \xi > 0 \). The parameter \( r \) is the riskfree interest rate, and \( q \) is the dividend yield. Both are assumed to be constant over time. \( \kappa \) is the speed of mean reversion to the mean reversion level \( \theta \), and \( \xi \) is the so-called volatility of volatility. \( W_t \) and \( Z_t \) are two correlated Brownian motions with \( dW_t dZ_t = \rho dt \) where \( \rho \in (-1, 1) \) is the correlation coefficient. The Feller condition \( \kappa \theta > \frac{1}{2} \xi^2 \) guarantees that the variance process never reaches zero and always stays positive. For practical uses it is also worth mentioning that in most cases the correlation coefficient \( \rho \) is negative. This means that an up-move in the asset is normally accompanied by a down-move in volatility.

Let \( P^E(S, V, t) \) be the current price of a European put option with strike price \( X \) and maturity \( T \). The option guarantees its holder a terminal payoff
given by

\[ P^E(S, V, T) = \max(X - S(T), 0). \]  

(2.3)

Using arbitrage arguments it is straightforward to derive a two dimensional partial differential equation (PDE) that must be satisfied by any derivative \( F \) written on \( S \) and \( V \):

\[ F_t + (r-q)SF_s + \frac{1}{2}VS^2F_{ss} + \kappa(\theta - V)F_v + \frac{1}{2}\xi^2V^2F_{vv} + \rho\xi VSF_{sv} - rF = 0, \]

on \( 0 < S, V < \infty, 0 < t < T \) (see Lewis (2000)). \( \lambda \) is called the market price of volatility risk. Heston provides some reasons for the assumption that \( \lambda \) is proportional to volatility, i.e. \( \lambda = k\sqrt{V} \) for some constant \( k \). Therefore \( \lambda\xi\sqrt{V} = k\xi V = \lambda^*V \) (say). Hence, without loss of generality \( \lambda \) can be set to zero as has been done in Guo and Hung (2007) or Ikonen and Toivanen (2007). For a constant volatility the two dimensional PDE reduces to the fundamental PDE due to Black/Scholes and Merton and admits a closed-form solution given by the celebrated BSM formula. If \( F \) is a European put option, i.e. \( F(S, V, t) = P^E(S, V, t) \), we have

\[ P^E_t + (r-q)SP^E_s + \frac{1}{2}VS^2P^E_{ss} + \kappa(\theta - V)P^E_v + \frac{1}{2}\xi^2V^2P^E_{vv} + \rho\xi VSP^E_{sv} - rP^E = 0 \]

(2.4)

where \( P^E(S, V, t) : \mathbb{R}^+ \times \mathbb{R}^+ \times [0, T] \rightarrow \mathbb{R}^+ \). The boundary conditions are given by

\[ P^E(S, V, T) = \max(X - S(T), 0) \]  

(2.5)

\[ P^E(0, V, t) = X e^{-r(T-t)}, \]  

(2.6)

\[ P^E(S, 0, t) = \max(X e^{-r(T-t)} - S(t)e^{-q(T-t)}, 0), \]  

(2.7)

\[ \lim_{S \to \infty} P^E(S, V, t) = 0, \]  

and

\[ \lim_{V \to \infty} P^E(S, V, t) = X e^{-r(T-t)}. \]  

(2.9)

\(^1\)Throughout this paper partial derivatives with respect to the underlying variables will be denoted by subscripts.
The first condition is the terminal condition. It specifies the final payoff of the option. The second condition states that for a stock price of zero the put price must equal the discounted strike price. The third condition specifies the payoff for a variance (volatility) of zero. In this case the underlying asset evolves completely deterministic and the put price equals its lower bound derived by arbitrage considerations. The next condition describes the option’s price for ever increasing asset prices. Obviously, since a put option gives its holder the right to sell the asset the price will tend to zero if \( S \) tends to infinity. Finally, notice that if variance (volatility) becomes infinite the current asset price contains no information about the terminal payoff of the derivative security, except that the put entitles its holder to sell the asset for \( X \). In this case the put price must equal the discounted strike price, i.e. its upper bound, again derived by arbitrage arguments.

In a similar manner the European call option pricing problem with solution \( C^E(S, V, t) \) is characterized as the unique solution of (2.4) subject to

\[
C^E(S, V, T) = \max(S(T) - X, 0), \\
C^E(0, V, t) = 0, \\
C^E(S, 0, t) = \max(S(t)e^{-q(T-t)} - Xe^{-r(T-t)}, 0), \\
\lim_{S \to \infty} C^E(S, V, t) = \infty,
\]

and

\[
\lim_{V \to \infty} C^E(S, V, t) = S(t)e^{-q(T-t)}. 
\]

### 3 Analytic Solution using Mellin Transforms

The objective of this section is to solve equation (2.4) subject to (2.5)-(2.9) in closed-form. The derivation of a solution is based on Mellin transforms. For a locally Lebesgue integrable function \( f(x), x \in \mathbb{R}^+ \), the Mellin transform
$M(f(x), \omega)$, $\omega \in \mathbb{C}$, is defined by

$$M(f(x), \omega) := \tilde{f}(\omega) = \int_0^\infty f(x) x^{\omega - 1} dx.$$ 

As a complex function the Mellin transform is defined on a vertical strip in the $\omega$-plane, whose boundaries are specified by the asymptotic behavior of the function $f(x)$ as $x \to 0^+$ and $x \to \infty$\(^2\). For conditions that guarantee the existence and the connection to Fourier and Laplace transforms, see Titchmarsh (1986) or Sneddon (1972). Conversely, if $f(x)$ is a continuous, integrable function with fundamental strip $(a, b)$, then if $c$ is such that $a < c < b$ and $f(c + it)$ is integrable, the inverse of the Mellin transform is given by

$$f(x) = M^{-1}(\tilde{f}(\omega)) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \tilde{f}(\omega) x^{-\omega} d\omega.$$ 

Let $\tilde{P}^E = \tilde{P}^E(\omega, V, t)$ denote the Mellin transform of $P^E(S, V, t)$. It is easily verified that $\tilde{P}^E$ exists in the entire halfplane with $Re(\omega) > 0$, where $Re(\omega)$ denotes the real part of $\omega$. A straightforward application to (2.4) gives

$$\tilde{P}^E_t + (a_1 V + b_1)\tilde{P}^E_V + (a_2 V + b_2)\tilde{P}^E_{VV} + (a_0 V + b_0)\tilde{P}^E = 0,$$  \hspace{1cm} (3.1)

where

$$a_1 = -(\omega \rho \xi + \kappa), \hspace{1cm} b_1 = \kappa \theta$$
$$a_2 = \frac{1}{2} \xi^2, \hspace{1cm} b_2 = 0$$
$$a_0 = \frac{1}{2} \omega (\omega + 1), \hspace{1cm} b_0 = q\omega - r(\omega + 1).$$  \hspace{1cm} (3.2)

This is a one dimensional PDE in the complex plane with non-constant coefficients. To provide a unique solution for $0 < V < \infty, 0 < t < T$ we

\(^2\)Fourier transforms (at least those which are typical in option pricing) usually exist in horizontal strips of the complex plane. This is the key conceptual difference between the two frameworks.
need to incorporate the boundary conditions from the previous section. The transformed terminal and boundary conditions are given by, respectively,

\[
\tilde{P}^E(\omega, V, T) = X^{\omega+1}\left(\frac{1}{\omega} - \frac{1}{\omega + 1}\right) \quad (3.3)
\]
\[
\tilde{P}^E(\omega, 0, t) = e^{(q\omega - r(\omega + 1))(T-t)} \cdot X^{\omega+1}\left(\frac{1}{\omega} - \frac{1}{\omega + 1}\right) \quad (3.4)
\]
and condition (2.9) becomes

\[
\lim_{V \to \infty} |\tilde{P}^E(\omega, V, t)| = \infty. \quad (3.5)
\]

Now, we change the time variable from \(t\) to \(\tau = T - t\) and convert the backward in time PDE into a forward in time PDE with solution domain \(0 < V, \tau < \infty\). With \(\tilde{P}^E(\omega, V, t) = \tilde{P}^E(\omega, V, \tau)\) the resulting equation is

\[
-\tilde{P}_\tau + (a_1 V + b_1)\tilde{P}_V + (a_2 V + b_2)\tilde{P}_{VV} + (a_0 V + b_0)\tilde{P} = 0, \quad (3.6)
\]
where the coefficients \(a_0, a_1, a_2, b_0, b_1\) and \(b_2\) are given in (3.2) and the terminal condition (3.3) becomes an initial condition

\[
\tilde{P}^E(\omega, V, 0) = X^{\omega+1}\left(\frac{1}{\omega} - \frac{1}{\omega + 1}\right). \quad (3.7)
\]

Additionally we have

\[
\tilde{P}^E(\omega, 0, \tau) = e^{(q\omega - r(\omega + 1))\tau} \cdot X^{\omega+1}\left(\frac{1}{\omega} - \frac{1}{\omega + 1}\right), \quad (3.8)
\]
and

\[
\lim_{V \to \infty} |\tilde{P}^E(\omega, V, \tau)| = \infty. \quad (3.9)
\]

To simplify the PDE (3.6) further we assume that the solution \(\tilde{P}^E(\omega, V, \tau)\) can be written in the form

\[
\tilde{P}^E(\omega, V, \tau) = e^{(q\omega - r(\omega + 1))\tau} \cdot h(\omega, V, \tau) \quad (3.10)
\]
with an appropriate function \(h(\omega, V, \tau)\). It follows that \(h\) must satisfy

\[
-h_\tau + (a_1 V + b_1)h_V + a_2 V h_{VV} + a_0 V h = 0, \quad (3.11)
\]
with initial and boundary conditions

\[
\begin{align*}
    h(\omega, V, 0) &= X^{\omega+1} \left( \frac{1}{\omega} - \frac{1}{\omega + 1} \right) \\
    h(\omega, 0, \tau) &= X^{\omega+1} \left( \frac{1}{\omega} - \frac{1}{\omega + 1} \right)
\end{align*}
\] (3.12)

and

\[
\lim_{V \to \infty} |h(\omega, V, \tau)| = \infty. \tag{3.14}
\]

Observe that for \( \kappa = \theta = \xi = 0 \), i.e. if the stock price dynamics are given by the standard BSM model with constant volatility, the PDE for \( h \) is solved as

\[
h(\omega, V, \tau) = X^{\omega+1} \left( \frac{1}{\omega} - \frac{1}{\omega + 1} \right) e^{\frac{1}{2} \omega (\omega+1) V \tau}. \tag{3.15}
\]

In this case the equation for \( \tilde{P}^E(\omega, V, \tau) \) becomes

\[
\tilde{P}^E(\omega, V, \tau) = X^{\omega+1} \left( \frac{1}{\omega} - \frac{1}{\omega + 1} \right) e^{\frac{1}{2} \omega (\omega+1) V + q \omega - r (\omega+1) \tau}, \tag{3.16}
\]

and the price of a European put option can be expressed as

\[
P^E(S, V, \tau) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \tilde{P}^E(\omega, V, \tau) S^{-\omega} d\omega, \tag{3.17}
\]

with \( 0 < c < \infty \). Frontczak and Schöbel (2008) show that the last equation is equivalent to the BSM formula for European put options.

The final step in deriving a general solution for \( h \) or equivalently for \( \tilde{P}^E \) for a non-constant volatility is to assume the following functional form of the solution\(^3\):

\[
h(\omega, V, \tau) = \tilde{c} \cdot H(\omega, \tau) \cdot e^{G(\omega, \tau) q_0 V}, \tag{3.18}
\]

with \( H(\omega, 0) = 1, G(\omega, 0) = 0 \) and where we have set

\[
\tilde{c} = X^{\omega+1} \left( \frac{1}{\omega} - \frac{1}{\omega + 1} \right). \tag{3.19}
\]

---

\(^3\)The assumption on the general structure of the solution is justified by the Feller condition.
Inserting the functional form for \( h \) in (3.11), determining the partial derivatives and simplifying yields two ordinary differential equations (ODEs). We have

\[
G_\tau(\omega, \tau) = A \cdot G^2(\omega, \tau) + B \cdot G(\omega, \tau) + C, \tag{3.20}
\]

and

\[
H_\tau(\omega, \tau) = a_0 \cdot b_1 \cdot G(\omega, \tau) \cdot H(\omega, \tau) \tag{3.21}
\]

where \( A = a_0a_2, \ B = a_1, \) and \( C = 1. \) The ODE for \( G(\omega, \tau) \) is identified as a Riccati equation with constant coefficients. These types of equations also appear in frameworks based on Fourier transforms, see Heston (1993), Bates (1996) or Schöbel and Zhu (1999). Having solved for \( G, \) a straightforward calculation shows that \( H(\omega, \tau) \) equals

\[
H(\omega, \tau) = e^{a_0 b_1 \int_0^\tau G(\omega, x) dx}. \tag{3.22}
\]

Thus, we first present the solution for \( G. \) The transformation

\[
G(\omega, \tau) = \frac{1}{A} u(\omega, \tau) - \frac{B}{2A}
\]

gives

\[
u_\tau(\omega, \tau) = u^2(\omega, \tau) + \frac{4AC - B^2}{4}. \tag{3.23}\]

Note that this is a special case of the more general class of ODEs given by

\[
u_\tau(\omega, \tau) = au^2(\omega, \tau) + b \tau^n,
\]

with \( n \in \mathbb{N} \) and \( a \) and \( b \) constants. This class of ODEs has solutions of the form

\[
u(\omega, \tau) = -\frac{1}{a} \frac{F_\tau(\omega, \tau)}{F(\omega, \tau)},
\]

where

\[
F(\omega, \tau) = \sqrt{\tau} \left( c_1 J_{\frac{1}{2m}} \left( \frac{1}{m} \sqrt{ab} \tau^m \right) + c_2 Y_{\frac{1}{2m}} \left( \frac{1}{m} \sqrt{ab} \tau^m \right) \right).
\]
The parameters $c_1, c_2$ are again constants depending on the underlying boundary conditions, $m = \frac{1}{2}(n + 2)$ and $J$ and $Y$ are Bessel functions. See Polyanin and Zaitsev (2003) for a reference. Setting $m = 1$ and incorporating the boundary conditions, $u(\omega, \tau)$ is solved as

$$u(\omega, \tau) = \frac{k}{2A} \tan \left( \frac{1}{2} k \tau \right) + \frac{B}{k} \tan \left( \frac{1}{2} k \tau \right),$$

(3.24)

where we have set

$$k = k(\omega) = \sqrt{4AC - B^2} = \sqrt{\xi^2 \omega(\omega + 1) - (\omega \rho \xi + \kappa)^2}. \quad (3.25)$$

Thus, we immediately get

$$G(\omega, \tau) = -\frac{B}{2A} \frac{k}{2A} \tan \left( \frac{1}{2} k \tau \right) + \frac{B}{k} \tan \left( \frac{1}{2} k \tau \right)$$

$$= -\frac{B}{2A} \frac{k}{2A} \frac{k \sin \left( \frac{1}{2} k \tau \right) + B \cos \left( \frac{1}{2} k \tau \right)}{k \cos \left( \frac{1}{2} k \tau \right) - B \sin \left( \frac{1}{2} k \tau \right)}. \quad (3.26)$$

Using $k^2 + B^2 = 4A$ is easily verified that an equivalent expression for $G(\omega, \tau)$ equals

$$G(\omega, \tau) = \frac{2 \sin \left( \frac{1}{2} k \tau \right)}{k \cos \left( \frac{1}{2} k \tau \right) + (\omega \rho \xi + \kappa) \sin \left( \frac{1}{2} k \tau \right)}. \quad (3.27)$$

with $k = k(\omega)$ from above. To solve for $H(\omega, \tau)$ we first mention that (Gradshteyn and Ryzhik (2007))

$$\int \frac{B \cos x + C \sin x}{b \cos + c \sin x} \, dx = \frac{Bc - Cb}{b^2 + c^2} \ln(b \cos x + c \sin x) + \frac{Bb + Cc}{b^2 + c^2} x.$$ 

Therefore,

$$\int_0^\tau G(\omega, x) \, dx = -\frac{B \tau}{2A} + \frac{1}{A} \ln \left( \frac{k}{k \cos \left( \frac{1}{2} k \tau \right) - B \sin \left( \frac{1}{2} k \tau \right)} \right) \quad (3.28)$$

and

$$H(\omega, \tau) = e^{\omega \tau} \left[ (\omega \rho \xi + \kappa) \tau + 2 \ln \left( \frac{k}{k \cos \left( \frac{1}{2} k \tau \right) + (\omega \rho \xi + \kappa) \sin \left( \frac{1}{2} k \tau \right)} \right) \right]. \quad (3.29)$$

Finally, we have arrived at the following result:
Theorem 3.1 A new Mellin-type pricing formula for European put options in Heston’s (1993) mean reverting stochastic volatility model given by

\[ P^E(S, V, \tau) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \tilde{P}^E(\omega, V, \tau) S^{-\omega} \, d\omega, \quad (3.30) \]

with \(0 < c < c^*\) and where

\[ \tilde{P}^E(\omega, V, \tau) = \tilde{c} \cdot e^{(q\omega - r(\omega + 1))\tau} \cdot H(\omega, \tau) \cdot e^{G(\omega, \tau) a_0 V}. \quad (3.31) \]

with \(G(\omega, \tau)\) and \(H(\omega, \tau)\) from above. The parameters \(\tilde{c}\) and \(k\) are given in (3.19) and (3.25), respectively. The choice of \(c^*\) will be commented below.

Remark 3.2 Note that similar to Carr and Madan (1999) the final pricing formula only requires a single integration.

We now consider the issue of specifying \(c^*\). Recall that to guarantee the existence of the inverse Mellin transform of \(\tilde{P}^E(\omega, V, \tau)\) in a vertical strip of the \(\omega\)-plane, we need \(\tilde{P}^E(c + iy, V, \tau)\) to be integrable, and hence analytic. From (3.27) and (3.29) we have that \(G(\omega, \tau)\) and \(H(\omega, \tau)\) have the same points of singularity with

\[
\lim_{\omega \to 0} G(\omega, \tau) = \frac{2 \sin \left( \frac{1}{2} i \kappa \tau \right)}{i \kappa \cos \left( \frac{1}{2} i \kappa \tau \right) + \kappa \sin \left( \frac{1}{2} i \kappa \tau \right)} \\
= \frac{2}{i \kappa} \sin \left( \frac{1}{2} i \kappa \tau \right) e^{\frac{1}{2} i \kappa \tau} \\
= \frac{1 - e^{-\kappa \tau}}{\kappa}, \quad (3.32)
\]

and

\[
\lim_{\omega \to 0} H(\omega, \tau) = 1. \quad (3.33)
\]

Furthermore, since

\[ k(\omega) = \sqrt{\xi^2 \omega^2 (1 - \rho^2) + \omega (\xi^2 - 2 \rho \xi \kappa) - \kappa^2}, \quad (3.34) \]
it follows that \( k(\omega) \) has two real roots given by

\[
\omega_{1/2} = \frac{-(\xi - 2\rho\kappa) \pm \sqrt{(\xi - 2\rho\kappa)^2 + 4\kappa^2(1 - \rho^2)}}{2\xi(1 - \rho^2)},
\]

(3.35)

where \( \rho \neq \pm 1 \) and where only the positive root \( \omega_1 \) is of relevance. For \( \rho = \pm 1 \) we have a single root

\[
\omega_1 = \frac{\kappa^2}{\xi^2 \mp 2\xi\kappa}.
\]

(3.36)

We deduce that all singular points of \( G \) and \( H \) are real, starting with \( \omega_1 \) being a removable singularity. We therefore define \( c^* \) as the first non-removable singularity of \( G \) and \( H \) in \( \{ \omega \in \mathbb{C} \mid 0 < Re(\omega) < \infty, Im(\omega) = 0 \} \), i.e. the first real root of

\[
f(\omega) = k(\omega) \cos \left( \frac{1}{2} k(\omega) \tau \right) + (\omega \rho \xi + \kappa) \sin \left( \frac{1}{2} k(\omega) \tau \right)
\]

(3.37)

except \( \omega_1 \). If \( f(\omega) \) has no roots or no other roots except \( \omega_1 \) in \( \{ \omega \in \mathbb{C} \mid 0 < Re(\omega) < \infty, Im(\omega) = 0 \} \) we set \( c^* = \infty \). By definition it follows that \( \omega_1 \leq c^* \), with the special cases \( \lim_{\tau \to 0} c^* = \infty \), and \( \lim_{\tau \to \infty} c^* = \omega_1 \).

4 Further Analysis

In the previous section a Mellin transform approach was used to solve the European put option pricing problem in Heston’s mean reverting stochastic volatility model. The outcome is a new characterization of European put prices using an integration along a vertical line segment in a strip of the positive complex half plane. Our solution has a clear and well defined structure. The numerical treatment of the solution is simple and requires a single integration procedure. However, the final expression for the option’s price can still be modified to provide further insights on the analytical solution. First we have the following proposition.
Proposition 4.1 An equivalent (and more convenient) way of expressing the solution in Theorem 3.1 is:

\[ P_E(S, V, \tau) = X e^{-r\tau} P_1 - S e^{-q\tau} P_2, \]  

(4.1)

with \( S = S(t) \) being the current stock price,

\[ P_1 = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \left( \frac{X e^{-r\tau}}{S e^{-q\tau}} \right) \frac{1}{\omega} H(\omega, \tau) e^{G(\omega, \tau) a_0 V} d\omega, \]  

(4.2)

and

\[ P_2 = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \left( \frac{X e^{-r\tau}}{S e^{-q\tau}} \right) \frac{1}{\omega + 1} H(\omega, \tau) e^{G(\omega, \tau) a_0 V} d\omega, \]  

(4.3)

where \( 0 < c < c^* \).

PROOF: The statement follows directly from Theorem 3.1 by simple rearrangement. \( \square \)

Remark 4.2 Equation (4.1) together with (4.2) and (4.3) provides a direct connection to Heston’s original pricing formula given by

\[ P_E(S, V, \tau) = X e^{-r\tau} \Pi_1 - S e^{-q\tau} \Pi_2, \]  

(4.4)

with

\[ \Pi_1 = \frac{1}{2} - \frac{1}{\pi} \int_0^\infty \operatorname{Re} \left( \frac{e^{-i\omega \ln X} \varphi(\omega)}{i\omega} \right) d\omega, \]  

(4.5)

and

\[ \Pi_2 = \frac{1}{2} - \frac{1}{\pi} \int_0^\infty \operatorname{Re} \left( \frac{e^{-i\omega \ln X} \varphi(\omega - i)}{i\omega \varphi(-i)} \right) d\omega, \]  

(4.6)

where the function \( \varphi(\omega) \) is the log-characteristic function of the stock at maturity \( S(T) \):

\[ \varphi(\omega) = E\left[ e^{i\omega \ln S(T)} \right]. \]  

(4.7)
Remark 4.3 By the fundamental concept of a risk-neutral valuation we have

\[ P_E(S, V, \tau) = E_i^Q \left[ e^{-r\tau}(X - S(T)) \cdot 1_{\{S(T) < X\}} \right] \]

\[ = Xe^{-r\tau} E_i^Q \left[ 1_{\{S(T) < X\}} \right] - Se^{-q\tau} E_i^{Q^*} \left[ 1_{\{S(T) < X\}} \right], \]

with \( E_t \) being the time \( t \) expectation under the corresponding risk-neutral probability measure, while \( Q^* \) denotes the equivalent martingale measure given by the Radon-Nikodym derivative

\[ \frac{dQ^*}{dQ} = \frac{S(T)e^{-r\tau}}{Se^{-q\tau}}. \]

So the framework allows an expression of the above probabilities as the inverse of Mellin transforms.

A further advantage of the new framework is that hedging parameters, commonly known as Greeks, are easily determined analytically. The most popular Greek letters widely used for risk management are delta, gamma, vega, rho, and theta. Each of these sensitivities measures a different dimension of risk inherent in the option. The results for Greeks are summarized in the next proposition.

Proposition 4.4 Setting

\[ I(\omega, \tau) = H(\omega, \tau)e^{G(\omega, \tau)a_0V}, \]

the analytical expressions for the delta, gamma, vega, rho, and theta in the case of European put options are given by, respectively,

\[ P_S^E(S, V, \tau) = \frac{-1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \left( \frac{X}{S} \right)^{\omega+1} \frac{1}{\omega + 1} e^{(q\omega - r(\omega + 1))\tau} I(\omega, \tau) d\omega, \quad (4.8) \]

\[ P_{SS}^E(S, V, \tau) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{1}{S} \left( \frac{X}{S} \right)^{\omega+1} e^{(q\omega - r(\omega + 1))\tau} I(\omega, \tau) d\omega, \quad (4.9) \]

\[ P_V^E(S, V, \tau) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{X}{2} \left( \frac{X}{S} \right)^{\omega} e^{(q\omega - r(\omega + 1))\tau} G(\omega, \tau) I(\omega, \tau) d\omega. \quad (4.10) \]
Recall that the rho of a put option is the partial derivative of $P^E$ with respect to the interest rate and equals

$$P^E_r(S, V, \tau) = -\frac{X}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{\omega}{S} \frac{1}{\omega} e^{(q\omega-r(\omega+1))\tau} I(\omega, \tau) d\omega. \quad (4.11)$$

Finally, the theta of the put, i.e. the partial derivative of $P^E$ with respect to $\tau$ is determined as

$$P^E_\tau(S, V, \tau) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} X \left( \frac{X}{S} \right) \frac{1}{\omega} e^{(q\omega-r(\omega+1))\tau} I(\omega, \tau) J(\omega, \tau) d\omega, \quad (4.12)$$

with

$$J(\omega, \tau) = q\omega - r(\omega + 1) + \frac{1}{2} \omega (\omega + 1) (\kappa \theta G(\omega, \tau) + V G(\omega, \tau)), \quad (4.13)$$

where

$$G(\omega, \tau) = \left( 1 - \frac{(\omega \rho \xi + \kappa)^2}{\xi^2 \omega (\omega + 1)} \right) \frac{1}{\cos^2 \left( \frac{1}{2} k \tau + \tan^{-1} \left( \frac{-(\omega \rho \xi + \kappa)}{k} \right) \right)}. \quad (4.14)$$

PROOF: The expressions follow directly from Theorem 3.1 or Proposition 4.1. The final expression for $I(\omega, \tau)$ follows by straightforward differentiation and (3.21). □

We point out that instead of using the put call parity relationship for valuing European call options a direct Mellin transform approach is also possible. However, a slightly modified definition is needed to guarantee the existence of the integral. We therefore propose to define the Mellin transform for calls as

$$M(C^E(S, V, t), \omega) = \tilde{C}^E(\omega, V, t) = \int_0^{\infty} C^E(S, V, t) S^{-(\omega+1)} dS, \quad (4.15)$$

where $1 < \text{Re}(\omega) < \infty$. Conversely, the inverse of this modified Mellin transform is given by

$$C^E(S, V, t) = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \tilde{C}^E(\omega, V, t) S^\omega d\omega, \quad (4.16)$$
where \( 1 < c \). Using the modification and following the lines of reasoning outlined in Section 3 it is straightforward to derive at

**Theorem 4.5** The Mellin-type closed-form valuation formula for European call options in the square-root stochastic volatility model of Heston (1993) equals

\[
C^E(S, V, \tau) = Se^{-q\tau} P_2^* - X e^{-r\tau} P_1^*,
\]

where

\[
P_2^* = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \left( \frac{Se^{-q\tau}}{Xe^{-r\tau}} \right)^{\omega-1} \frac{1}{\omega - 1} H^*(\omega, \tau)e^{G^*(\omega, \tau) a_0^* V} d\omega,
\]

and

\[
P_1^* = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \left( \frac{Se^{-q\tau}}{Xe^{-r\tau}} \right)^{\omega} \frac{1}{\omega - 1} H^*(\omega, \tau)e^{G^*(\omega, \tau) a_0^* V} d\omega,
\]

with

\[
H^*(\omega, \tau) = e^{\frac{\omega\theta}{2}} \left[ -\omega(\rho\xi - \kappa)\tau + 2\ln\left( \frac{k^* \cos\left(\frac{1}{2}k^*\tau\right) - \kappa}{k^* \cos\left(\frac{1}{2}k^*\tau\right) - (\omega\rho\xi - \kappa) \sin\left(\frac{1}{2}k^*\tau\right)} \right) \right],
\]

\[
G^*(\omega, \tau) = \frac{2\sin\left(\frac{1}{2}k^*\tau\right)}{k^* \cos\left(\frac{1}{2}k^*\tau\right) - (\omega\rho\xi - \kappa) \sin\left(\frac{1}{2}k^*\tau\right)},
\]

\[
k^* = k^*(\omega) = \sqrt{\xi^2\omega(\omega - 1) - (\omega\rho\xi - \kappa)^2},
\]

and \( a_0^* = \frac{1}{2}\omega(\omega - 1) \). Furthermore, we have that \( 1 < c < c^* \) with \( c^* \) being characterized equivalently as at the end of the previous section.

**Remark 4.6** Again, a direct analogy to Heston’s original pricing formula is provided. Also, the corresponding closed-form expressions for the Greeks follow immediately.

## 5 Numerical Examples

In this section we evaluate the results of the previous sections for the purpose of computing and comparing option prices for a range of different parameter
combinations. Since our numerical calculations are not based on a calibration procedure we will use notional parameter specifications. As a benchmark we choose the pricing formula due to Heston based on Fourier inversion (H). From the previous analysis it follows that the numerical inversion in both integral transform approaches requires the calculation of logarithms with complex arguments. As pointed out by Schöbel and Zhu (1999) and Kahl and Jäckel (2005) this calculation may cause problems especially for options with long maturities or high mean reversion levels. We therefore additionally implement the rotation count algorithm proposed by the second authors to overcome these possible inconsistencies (H(RCA)). The Mellin transform solution (MT) is based on equations (4.1) for puts and (4.17) for calls, respectively. The limits of integration \( c \pm i\infty \) are truncated at \( c \pm i500 \). Although any other choice of truncation is possible this turned out to provide comparable results. To assess the accuracy of the alternative solutions we determine the absolute difference between H(RCA) and MT (Diff). Table 1 gives a first look at the results for different asset prices and expiration dates. We distinguish between in-the-money (ITM), at-the-money (ATM), and out-of-the-money (OTM) options. Fixed parameters are \( X = 100, r = 0.04, q = 0.02, V = 0.09, \kappa = 3, \theta = 0.12, \xi = 0.2, \) and \( \rho = -0.5 \), whereas \( S \) and \( \tau \) vary from 80 to 120 currency units, and three months to three years, respectively. Using these values we have for the European put \( \omega_1 = 9.6749 \) constant, while \( c^* \) varies over time from 54.7066 (\( \tau = 0.25 \)) to 11.7046 (\( \tau = 3.0 \)) and for the European call \( \omega_1 = 31.0082 \) with \( c^* \) changing from 116.7385 (\( \tau = 0.25 \)) to 33.7810 (\( \tau = 3.0 \)). We therefore use \( c = 2 \) for the calculations (in both cases). Our major finding is that the pricing formulae derived in this paper provide comparable results for all parameter combinations. The absolute differences are very small (of order \( 10^{-6} \) to \( 10^{-8} \) for puts and \( 10^{-5} \) to \( 10^{-8} \) for calls). They can be neglected from a practical point of view. In addition, since the numerical integration is accomplished in both frameworks equivalently efficient, the calculations are done very quickly.
Comparison of European option prices in Heston’s stochastic volatility model for different asset prices $S$ and maturities $\tau$. Fixed parameters are $X = 100$, $r = 0.04$, $q = 0.02$, $V = 0.09$, $\kappa = 3$, $\theta = 0.12$, $\xi = 0.2$, $\rho = -0.5$, and $c = 2$.

Next, we also examine how the option prices vary if the correlation between the underlying asset and its instantaneous variance changes. Although from a practical point of view it may be less realistic to allow for a positive correla-

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Table 1:

Next, we also examine how the option prices vary if the correlation between the underlying asset and its instantaneous variance changes. Although from a practical point of view it may be less realistic to allow for a positive correla-
tion we do not make any restrictions on $\rho$ and let it range from $-1.00$ to $1.00$. We fix time to maturity to be 6 months. Also, to provide a variety of parameter combinations we change some of the remaining parameters slightly: $X = 100$, $r = 0.05$, $q = 0.02$, $V = 0.04$, $\kappa = 2$, $\theta = 0.05$, and $\xi = 0.2$. We abstain from presenting the numerical values of $\omega_1$ and $c^*$ in this case and choose again $c = 2$ for the integration. Our findings are reported in Table 2. Again, the Mellin transform approach gives very satisfactory results as the absolute differences show. For both puts and calls they are of order $10^{-5}$ to $10^{-6}$. Analyzing the results in detail one basically observes two different kinds of behavior. For ITM put options we have an increase in value for increasing values of $\rho$. The maximum difference is 0.6655 or 3.60%. The opposite is true for OTM puts. Here we have an strict decline in price if $\rho$ is increased. The magnitude of price reactions to changes in $\rho$ increases, too. The maximum change in the downward move is 0.7787 or equivalently 75.21%. The same behavior is observed for ATM options. However, the changes are much more moderate with a maximum percentage change of 0.80%. For European calls the situation is different. OTM calls increase significantly in value if $\rho$ is increased whereas ITM and ATM call prices decrease for an increasing $\rho$. The maximum percentage changes are 492.96% (OTM), 3.49% (ITM), and 0.62% (ATM), respectively. Our numerical experiments suggest that the new framework is flexible enough to account for all the pricing features inherent in the model.

6 Conclusion

We have applied a new integral transform approach for a closed-form valuation of European options on dividend paying stocks in a mean reverting stochastic volatility model with correlation. Using the new framework our main results are new analytical characterizations of options’ prices and hedg-
ing parameters. Our equivalent solutions may be of interest for theorists as well as practitioners. On one hand they provide further insights on the analytic solution, on the other hand they are easily and quickly treated numerically by applying efficient numerical integration schemes. We have done extensive numerical tests to demonstrate the flexibility and to assess the accuracy of the alternative pricing formulae. We have shown that the results are very gratifying and convincing. The new method is very competitive and should be regarded as a real alternative to other approaches, basically Fourier inversion methods, existing in the literature. Also, since the transformation variable is the current value of the asset instead of its terminal price the new framework may turn out to be applicable to path dependent problems.
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<td>5.7 · 10^-6</td>
</tr>
<tr>
<td>(120; 1.00)</td>
<td>0.2566</td>
<td>0.2566</td>
<td>0.2566</td>
<td>1.3 · 10^-6</td>
<td>21.5316</td>
<td>21.5316</td>
<td>21.5316</td>
<td>2.0 · 10^-6</td>
</tr>
</tbody>
</table>

Table 2: Comparison of European option prices for different asset prices S and correlations ρ. Fixed parameters are $X = 100$, $r = 0.05$, $q = 0.02$, $V = 0.04$, $\kappa = 2$, $\theta = 0.05$, $\xi = 0.2$, and $c = 2$. 

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